





#### oneAPI DevSummit for HPC and AI

6-7 December 2022

Marcel Breyer

> Performance Evolution of Different SYCL Implementations on the Basis of PLSSVM

## **Motivation**



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## **Motivation**

- Previous publication 6 months ago: "A Comparison of SYCL, OpenCL, CUDA, and OpenMP for Massively Parallel Support Vector Machine Classification on Multi-Vendor Hardware"
- most of the time OpenCL was faster than SYCL
- but SYCL has drastically better usability

#### *Could SYCL close the performance gap to OpenCL in our # data points # data points use case?*





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What to know about **PLSSVM** 

1

## Support Vector Machines (SVMs) and their problems $\left| \begin{array}{c} \bullet & \bullet \\ \circ & \bullet \\ \circ & \bullet \end{array} \right|$

- SVMs as supervised machine learning technique
- originally meant for binary classification



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  - → state-of-the-art: Sequential Minimal Optimization (SMO) (proposed by Platt in 1998)
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   still not well suited for modern, highly parallel hardware



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## ➔ Least Squares Support Vector Machine (LS-SVM)

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## ➔ Least Squares Support Vector Machine (LS-SVM)

(proposed by Suykens and Vandewalle in 1999)

- reformulation of standard SVM to solving a system of linear equations
- massively parallel algorithms known



LS-SVMs solve the system of linear equations:

$$\begin{bmatrix} \boldsymbol{Q} & \vec{1}_n \\ \vec{1}_n^T & 0 \end{bmatrix} \cdot \begin{bmatrix} \boldsymbol{\alpha} \\ b \end{bmatrix} = \begin{bmatrix} \boldsymbol{y} \\ 0 \end{bmatrix}$$

where Q is the kernel matrix according to

$$Q_{ij} = k(\vec{x}_i, \vec{x}_j) + \frac{1}{C} \cdot \delta_{ij}$$
 (with  $\delta_{ij} = \begin{cases} 1 & i = j \\ 0 & \text{else} \end{cases}$ )

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→ Conjugate Gradient algorithm: (variant of Shewchuk et al.)

 $1 \cdot i \leftarrow 0$ 2:  $r \leftarrow h - Ar$  $3 \cdot d \leftarrow r$ 4.  $\delta_{max} \leftarrow r^T r$ 5:  $\delta_0 \leftarrow \delta_{new}$ 6: while  $i < i_{max}$  and  $\delta_{new} > \epsilon^2 \delta_0$  do 7:  $a \leftarrow Ad$ 8:  $\alpha \leftarrow \frac{\delta_{new}}{dTa}$ 9:  $x \leftarrow x + \alpha d$ 10: **if** i is divisible by 50 **then** 11:  $r \leftarrow b - Ax$ 12. else 13:  $r \leftarrow r - \alpha q$ 14: end if 15  $\delta_{old} \leftarrow \delta_{new}$ 16:  $\delta_{new} \leftarrow r^T r$ 17:  $\beta \leftarrow \frac{\delta_{new}}{\delta_{new}}$ 18:  $d \leftarrow r + \beta d$  $i \leftarrow i + 1$ 19. 20: end while

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Setup or constant operations

1: 
$$\epsilon \leftarrow 0$$
  
2:  $r \leftarrow b - Ax$   
3:  $l \leftarrow T$   
4:  $\delta_{new} \leftarrow r^T r$   
5:  $bo \leftarrow \delta_{new}$   
6: while  $i < i_{max}$  and  $\delta_{new} > \epsilon^2 \delta_0$  do  
7:  $q \leftarrow Ad$   
8:  $\alpha \leftarrow \frac{\delta_{new}}{d^T q}$   
9:  $x \leftarrow x + \alpha d$   
10: if *i* is divisible by 50 then  
11:  $r \leftarrow b - Ax$   
12: else  
13:  $r \leftarrow r - \alpha q$   
14: end if  
15:  $\delta_{old} \leftarrow \delta_{new}$   
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→ Conjugate Gradient algorithm: (variant of Shewchuk et al.)

Setup or constant operation
 BLAS local 1

$$\rightarrow$$
 host  $\rightarrow$  host

1: 
$$i \leftarrow 0$$
  
2:  $r \leftarrow b - Ax$   
3:  $d \leftarrow 1$   
4:  $\delta_{new} \leftarrow r^T r$   
5:  $\delta_0 \leftarrow \delta_{new}$   
6: while  $i < i_{max}$  and  $\delta_{new} > \epsilon^2 \delta_0$  do  
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→ Conjugate Gradient algorithm: (variant of Shewchuk et al.)

- Setup or constant operations
  BLAS Level 1
- BLAS Level

- → host
  → host
  - → device



→ host

→ host

 $\rightarrow$  device

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   BLAS Level 1
  - BLAS Level

.

$$\mathbf{a} \in \mathbb{R}^{\mathsf{num\_data\_points \times num\_data\_points}}$$

1. 2: 3. 4:  $rew \leftarrow r$ 5: while  $i < i_{max}$  and  $\delta_{new} > \epsilon^2 \delta_0$  do 6: 7: 8. 9:  $\leftarrow x + \alpha i$  $10 \cdot$ if i is divisible by 50 then 11: 12: else 13:  $\leftarrow r - \alpha a$ 14: end if 15 16:  $n_{ew} \leftarrow$ 17: 18.  $\leftarrow r + \beta_0$ 19. 20. end while

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→ host

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 $\Rightarrow$  Q is symmetric positive-definite

→ Conjugate Gradient algorithm: (variant of Shewchuk et al.)

- Setup or constant operations
   BLAS Level 1
- BLAS Level 2
- $\Rightarrow Q \in \mathbb{R}^{\mathsf{num\_data\_points} \times \mathsf{num\_data\_points}}$
- $\rightarrow$  implicitly calculate Q in each iteration



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## **PLSSVM - Parallel Least Squares Support Vector Machine**

- modern C++17
- open source & on GitHub
- single and double precision via template parameter
- parallelizes matrix-vector multiplication in CG algorithm





https://github.com/SC-SGS/PLSSVM

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- backends: OpenMP, CUDA, HIP, OpenCL, and SYCL
- backend and target platform selectable at runtime
- multi-GPU support for linear kernel function
- drop-in replacement for LIBSVM's svm-train and svm-predict executables
- currently only binary classification and dense calculations





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## New results and findings

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### **NVIDIA A100**



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16 384 × 4096	DPC++ 20220202	DPC++ 20221102	CUDA
runtime	1.242 s	0.358 s	0.287 s

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sycl/handler.hpp (DPC++ 20220202)

```
template <typename KernelName, typename ElementType, typename KernelType>
 1
      SYCL KERNEL ATTR void
 2
    #ifdef SYCL NONCONST FUNCTOR
3
      kernel_parallel_for(KernelType KernelFunc) {
 Δ
 5
    #else
      kernel parallel for(const KernelType &KernelFunc) {
 6
 7
    #endif
    #ifdef SYCL DEVICE ONLY
8
        KernelFunc(detail::Builder::getElement(detail::declptr<ElementType>()));
9
    #else
10
        (void)KernelFunc:
11
12
    #endif
13
      }
                                             // 925'193'095 (divergent branches)
```

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atomics (instr. exec.)	1 418 372 005	30 117 888	18 097 152
register count	164	164	162
memory	more memory transfers involving shared memory and between global $\longleftrightarrow$ L1		better usage of registers; overall 43 % more memory throughput

#### AMD Radeon Pro VII



#### AMD Radeon Pro VII



## Basic idea of the used blocking scheme



Note: each matrix entry  $Q_{ij}$  is calculated using the kernel function  $k(\vec{x}_i, \vec{x}_j)!$  (e.g., dot products in the linear kernel)

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#### Basic idea of the used blocking scheme











#### AMD Radeon Pro VII: updated runtimes with blocking size 4



16 384 × 4096	HIP		OpenCL	
INTERNAL_BLOCKING_SIZE	4	6	4	6
runtime	0.891 s	6.930 s	1.335 s	1.275 s

16 384 × 4096	F	ΗP	Оре	nCL
INTERNAL_BLOCKING_SIZE	4	6	4	6
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vector general purpose register	64	64	56	108

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% of active VALU threads	84.69%	<b>89.88</b> ~%	99.29 %	<b>93.95</b> %

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avg number of VALU inst.	57561	156393	58062	112165
% of active VALU threads	84.69%	89.88%	99.29 %	<b>93.95</b> %
video memory fetches	84.29 GB	2039.79 GB	80.69 GB	53.48 GB
video memory writes	22.26 MB	1952.76 GB	19.45 MB	12.73 MB
bank conflicts (lower is better)	13.11%	0.10%	20.34 %	4.74%

#### Intel Xeon E-2146G



#### Intel Xeon E-2146G



#### Intel Xeon E-2146G



#### Key takeaways: new versions improve the performance

	DPC++		hipSYCL	
	nd_range	hierarchical	nd_range	hierarchical
NVIDIA A100	1	Ы	<b>→</b>	$\rightarrow$
AMD Radeon Pro VII	$\rightarrow$	<b>^</b>	$\mathbf{V}$	$\rightarrow$
Intel Xeon E-2146G	$\rightarrow$	R	<b>→</b> / <b>↑</b>	<b>→</b> /↓

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## Key takeaways: the performance portability is good

Performance portability (application efficiency): (proposed by Pennycook, Sewall, and Lee in 2016)

$$\Phi(a, p, H) = \begin{cases} \frac{|H|}{\sum_{i \in H} \frac{1}{e_i(a, p)}} & \text{if } i \text{ is supported } \forall i \in H \\ 0 & \text{otherwise} \end{cases}$$

a : an application(modified matrix-vector multiplication)p : a specific problem(16 384 × 4096)H : a set of platforms(NVIDIA A100, AMD Radeon Pro VII, Intel Xeon)

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CUDA	HIP	OpenMP
0 %	0 %	0 %

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$$\begin{split} \Psi(a,p,H) = \begin{cases} \frac{|H|}{\sum_{i \in H} \frac{1}{e_i(a,p)}} & \text{if } i \text{ is supported } \forall i \in H \\ 0 & \text{otherwise} \end{cases} \\ \text{an application} & (\text{modified matrix-vector multiplication}) \\ \text{a specific problem} & (16\,384\times4096) \end{cases} \end{split}$$

(NVIDIA A100, AMD Radeon Pro VII, Intel Xeon)

CUDA	HIP	OpenMP	OpenCL	DPC++	hipSYCL
0 %	0 %	0 %	49.28 %	70.77 %	52.40 %

a:p:

H: a set of platforms

#### Conclusion

- fine-tuning hyper parameter (like the blocking size) can have a major impact on the performance
- profiling SYCL code (DPC++ and hipSYCL) is as easy as profiling native code

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- installing new DPC++ or hipSYCL versions may drastically increase performance
- SYCL provides a better performance portability than OpenCL  $\rightarrow$  in our case, DPC++ has the best performance portability with  $\Phi(a, p, H) = 70.77\%$
- in addition: SYCL needs drastically less lines of code when compared to OpenCL
  - $\rightarrow$  in our case, more the 300 lines of code

#### Conclusion

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- profiling SYCL code (DPC++ and hipSYCL) is as easy as profiling native code
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   → in our case, more the 300 lines of code

## If performance portability is important, SYCL should be chosen over OpenCL!





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- https://orcid.org/0000-0003-3574-0650

## Further reading about PLSSVM

- Alexander Van Craen, Marcel Breyer, and Dirk Pflüger. "PLSSVM: A (multi-)GPGPU-accelerated Least Squares Support Vector Machine". In: 2022 IEEE International Parallel and Distributed Processing Symposium Workshops (IPDPSW). 2022, pp. 818–827. DOI: 10.1109/IPDPSW55747.2022.00138.
- [2] Marcel Breyer, Alexander Van Craen, and Dirk Pflüger. "A Comparison of SYCL, OpenCL, CUDA, and OpenMP for Massively Parallel Support Vector Machine Classification on Multi-Vendor Hardware". In: International Workshop on OpenCL. IWOCL'22. Bristol, United Kingdom, United Kingdom: Association for Computing Machinery, 2022. ISBN: 9781450396585. DOI: 10.1145/3529538.3529980. URL: https://doi.org/10.1145/3529538.3529980.
- [3] Alexander Van Craen, Marcel Breyer, and Dirk Pflüger. "PLSSVM—Parallel Least Squares Support Vector Machine". In: Software Impacts 14 (2022), p. 100343. ISSN: 2665-9638. DOI: https://doi.org/10.1016/j.simpa.2022.100343. URL: https://www.sciencedirect.com/science/article/pii/S2665963822000641.

# Additional

## resources

#### Basics of Support Vector Machines (SVMs) (proposed by Boser, Guyon, and Vapnik in 1992)



 $y = \operatorname{sgn}\left(\langle \vec{w}, \vec{x} \rangle + b\right)$ 

## **PLSSVM** supports many different backends



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## Different SYCL kernel invocation types

reverse all elements in an array



nd\_range (bottom-up) CUDA HIP OpenCL

hierarchical (top-down)

#### Used software and hardware



Source: www.nvidia.com



Source: www.amd.com



Source: www.intel.com

NVIDIA A100 CUDA 11.4.3 Driver Version 510.85.02

> DPC++ OpenSource LLVM fork

hipSYCL *OpenSource*  Radeon Pro VII ROCm 5.3.0 Driver Version 5.18.2.22.40 Intel Xeon E-2146G Intel DevCloud

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sycl-nightly/20220202 (February 02, 2022) sycl-nightly/20221102 (November 02, 2022)

develop 6962942 (February 01, 2022) develop 012e16d (October 20, 2022)

## **NVIDIA A100: varying blocking size**



#### **NVIDIA A100: the DPC++ compiler version makes a difference**



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## Key takeaways: SYCL needs less lines of code than OpenCL

	kernel function	device discovery	other setup and bookkeeping code
CUDA	67	-	-
HIP	67	-	-
OpenMP	29	-	-
OpenCL	65	96	<ul> <li>166 (kernel compilation &amp; caching)</li> <li>83 (custom sha256 for caching)</li> <li>60 (3 custom RAII classes)</li> <li>27 (custom atomic add)</li> <li>→ 336</li> </ul>
nd_range	71 99	77	20 (used function object)